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April 2013

## FAN3216 / FAN3217 Dual 2-A, High-Speed, Low-Side Gate Drivers

#### **Features**

- Industry-Standard Pinouts
- 4.5-V to 18-V Operating Range
- 3-A Peak Sink/Source at V<sub>DD</sub> = 12 V
- 2.4-A Sink / 1.6-A Source at V<sub>OUT</sub> = 6 V
- Inverting Configuration (FAN3216) and Non-Inverting Configuration (FAN3217)
- Internal Resistors Turn Driver Off If No Inputs
- 12-ns / 9-ns Typical Rise/Fall Times (1 nF Load)
- 20-ns Typical Propagation Delay Time Matched within 1 ns to the Other Channel
- TTL Input Thresholds
- MillerDrive<sup>™</sup> Technology
- Double Current Capability by Paralleling Channels
- Standard SOIC-8 Package
- Rated from –40°C to +125°C Ambient
- Automotive Qualified to AEC-Q100 (F085 Versions)

## **Applications**

- Switch-Mode Power Supplies
- High-Efficiency MOSFET Switching
- Synchronous Rectifier Circuits
- DC-to-DC Converters
- Motor Control
- Automotive-Qualified Systems (F085 Versions)

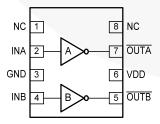


Figure 1. FAN3216 Pin Configuration

## **Description**

The FAN3216 and FAN3217 dual 2 A gate drivers are designed to drive N-channel enhancement-mode MOSFETs in low-side switching applications by providing high peak current pulses during the short switching intervals. They are both available with TTL input thresholds. Internal circuitry provides an undervoltage lockout function by holding the output LOW until the supply voltage is within the operating range. In addition, the drivers feature matched internal propagation delays between A and B channels for applications requiring dual gate drives with critical timing, such as synchronous rectifiers. This also enables connecting two drivers in parallel to effectively double the current capability driving a single MOSFET.

The FAN3216/17 drivers incorporate MillerDrive™ architecture for the final output stage. This bipolar-MOSFET combination provides high current during the Miller plateau stage of the MOSFET turn-on / turn-off process to minimize switching loss, while providing rail-to-rail voltage swing and reverse current capability.

The FAN3216 offers two inverting drivers and the FAN3217 offers two non-inverting drivers. Both are offered in a standard 8-pin SOIC package.

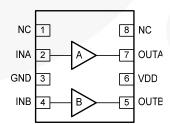


Figure 2. FAN3217 Pin Configuration

## **Ordering Information**

Part Number	Logic	Input Threshold	Package	Packing Method	Quantity per Reel
FAN3216TMX	Dual Inverting Channels	TTL	SOIC-8	Tape & Reel	2,500
FAN3216TMX_F085 <sup>(1)</sup>	Dual Inverting Channels	TTL	SOIC-8	Tape & Reel	2,500
FAN3217TMX	Dual Non-Inverting Channels	TTL	SOIC-8	Tape & Reel	2,500
FAN3217TMX_F085 <sup>(1)</sup>	Dual Non-Inverting Channels	TTL	SOIC-8	Tape & Reel	2,500

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#### Note:

1. Qualified to AEC-Q100

## **Package Outlines**

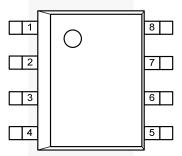


Figure 3. SOIC-8 (Top View)

## Thermal Characteristics<sup>(2)</sup>

Package	Θ <sub>JL</sub> <sup>(3)</sup>	Θ <sub>JT</sub> <sup>(4)</sup>	Θ <sub>JA</sub> <sup>(5)</sup>	$\Psi_{JB}^{(6)}$	$\Psi_{JT}^{(7)}$	Unit
8-Pin Small Outline Integrated Circuit (SOIC)	40	31	89	43	3.0	°C/W

#### Notes:

- 2. Estimates derived from thermal simulation; actual values depend on the application.
- 3. Theta\_JL (Θ<sub>JL</sub>): Thermal resistance between the semiconductor junction and the bottom surface of all the leads (including any thermal pad) that are typically soldered to a PCB.
- 4. Theta\_JT ( $\Theta_{JT}$ ): Thermal resistance between the semiconductor junction and the top surface of the package, assuming it is held at a uniform temperature by a top-side heatsink.
- Theta\_JA (Θ<sub>JA</sub>): Thermal resistance between junction and ambient, dependent on the PCB design, heat sinking, and airflow. The value given is for natural convection with no heatsink using a 2S2P board, as specified in JEDEC standards JESD51-2, JESD51-5, and JESD51-7, as appropriate.
- 6. Psi\_JB (ΨjB): Thermal characterization parameter providing correlation between semiconductor junction temperature and an application circuit board reference point for the thermal environment defined in Note 5. For the SOIC-8 package, the board reference is defined as the pcb copper adjacent to pin 6.
- 7. Psi\_JT (YjT): Thermal characterization parameter providing correlation between the semiconductor junction temperature and the center of the top of the package for the thermal environment defined in Note 5.

## **Pin Configurations**

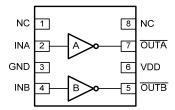


Figure 4. FAN3216

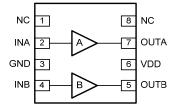


Figure 5. FAN3217

## **Pin Definitions**

Pin	Name	Pin Description
1	NC	No Connect. This pin can be grounded or left floating.
2	INA	Input to Channel A.
3	GND	Ground. Common ground reference for input and output circuits.
4	INB	Input to Channel B.
5 (FAN3216)	OUTB	<b>Gate Drive Output B</b> (inverted from the input): Held LOW unless required input is present and V <sub>DD</sub> is above UVLO threshold.
5 (FAN3217)	OUTB	<b>Gate Drive Output B</b> : Held LOW unless required input(s) are present and $V_{DD}$ is above UVLO threshold.
6	VDD	Supply Voltage. Provides power to the IC.
7 (FAN3216)	OUTA	<b>Gate Drive Output A</b> (inverted from the input): Held LOW unless required input is present and V <sub>DD</sub> is above UVLO threshold.
7 (FAN3217)	OUTA	<b>Gate Drive Output A</b> : Held LOW unless required input(s) are present and V <sub>DD</sub> is above UVLO threshold.
8	NC	No Connect. This pin can be grounded or left floating.

## **Output Logic**

FAN3216 (x=A or B)				
INx	OUTx			
0	1			
1 <sup>(8)</sup>	0			

FAN3217 (x=A or B)				
INx OUTx				
0(8)	0			
1	1			

#### Note:

8. Default input signal if no external connection is made.

## **Block Diagrams**

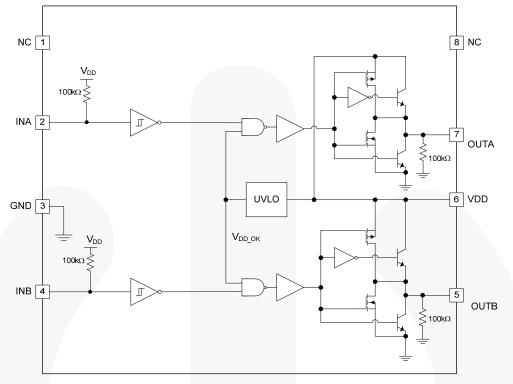


Figure 6. FAN3216 Block Diagram

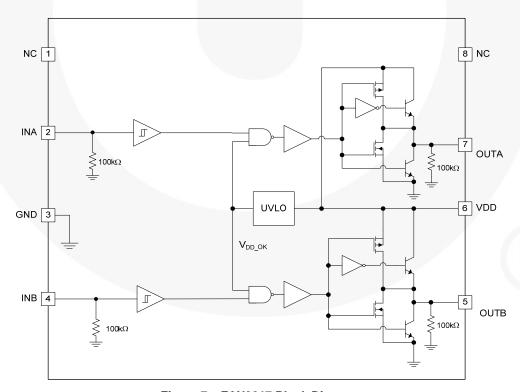


Figure 7. FAN3217 Block Diagram

## **Absolute Maximum Ratings**

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

Symbol	Parameter	Min.	Max.	Unit
$V_{DD}$	VDD to PGND	-0.3	20.0	٧
V <sub>IN</sub>	INA and INB to GND	GND - 0.3	V <sub>DD</sub> + 0.3	V
Vout	OUTA and OUTB to GND	GND - 0.3	V <sub>DD</sub> + 0.3	V
TL	Lead Soldering Temperature (10 Seconds)		+260	°C
TJ	Junction Temperature	-55	+150	°C
T <sub>STG</sub>	Storage Temperature	-65	+150	°C

## **Recommended Operating Conditions**

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to Absolute Maximum Ratings.

Symbol	Parameter	Min.	Max.	Unit
$V_{DD}$	Supply Voltage Range	4.5	18.0	V
$V_{IN}$	Input Voltage INA and INB	0	$V_{DD}$	V
T <sub>A</sub>	Operating Ambient Temperature	-40	+125	°C

## **Electrical Characteristics**

Unless otherwise noted,  $V_{DD}$ =12 V,  $T_J$ =-40°C to +125°C. Currents are defined as positive into the device and negative out of the device.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Supply			•			
$V_{DD}$	Operating Range		4.5		18.0	V
I <sub>DD</sub>	Supply Current, Inputs Not Connected			0.75	1.20	mA
$V_{ON}$	Turn-On Voltage	INA=V <sub>DD</sub> , INB=0 V	3.45	3.90	4.35	V
$V_{OFF}$	Turn-Off Voltage	INA=V <sub>DD</sub> , INB=0 V	3.25	3.70	4.15	V
FAN3216TM	IX_F085, FAN3217TMX_F085 (Automotive-	Qualified Versions)	ı			ı
V <sub>ON</sub>	Turn-On Voltage <sup>(11)</sup>	INA=V <sub>DD</sub> , INB=0 V	3.40	3.90	4.60	V
V <sub>OFF</sub>	Turn-Off Voltage <sup>(11)</sup>	INA=V <sub>DD</sub> , INB=0 V	3.20	3.70	4.30	V
Inputs						<u> </u>
V <sub>IL T</sub>	INx Logic Low Threshold		0.8	1.2		V
	INx Logic High Threshold			1.6	2.0	V
V <sub>HYS_T</sub>	TTL Logic Hysteresis Voltage		0.2	0.4	0.8	V
	IX, FAN3217TMX					
I <sub>IN+</sub>	Non-inverting Input Current	IN from 0 to V <sub>DD</sub>	-1.0		175	μA
I <sub>IN-</sub>	Inverting Input Current	IN from 0 to V <sub>DD</sub>	-175.0		1.0	μΑ
FAN3216TM	1X_F085, FAN3217TMX_F085 (Automotive-	Qualified Versions)				
I <sub>INx_T</sub>	Non-inverting Input Current <sup>(11)</sup>	IN=0 V	-1.5		1.5	μA
I <sub>INx_T</sub>	Non-inverting Input Current <sup>(11)</sup>	IN=V <sub>DD</sub>	90	120	175.0	μA
I <sub>INx_T</sub>	Inverting Input Current <sup>(11)</sup>	IN=0 V	-175.0	-120	-90	μA
I <sub>INx_T</sub>	Inverting Input Current <sup>(11)</sup>	IN=V <sub>DD</sub>	-1.5		1.5	μA
Outputs						
I <sub>SINK</sub>	OUT Current, Mid-Voltage, Sinking <sup>(9)</sup>	OUTx at V <sub>DD</sub> /2, C <sub>LOAD</sub> =0.22 μF, f=1 kHz		2.4	y	Α
I <sub>SOURCE</sub>	OUT Current, Mid-Voltage, Sourcing <sup>(9)</sup>	OUTx at V <sub>DD</sub> /2, C <sub>LOAD</sub> =0.1 µF, f=1 kHz		-1.6		Α
I <sub>PK_SINK</sub>	OUT Current, Peak, Sinking <sup>(9)</sup>	C <sub>LOAD</sub> =0.1 µF, f=1 kHz		3		Α
I <sub>PK_SOURCE</sub>	OUT Current, Peak, Sourcing <sup>(9)</sup>	C <sub>LOAD</sub> =0.1 µF, f=1 kHz		-3	7	Α
t <sub>RISE</sub>	Output Rise Time <sup>(10)</sup>	C <sub>LOAD</sub> =1000 pF		12	22	ns
t <sub>FALL</sub>	Output Fall Time <sup>(10)</sup>	C <sub>LOAD</sub> =1000 pF		9	17	ns
t <sub>D1</sub> , t <sub>D2</sub>	Output Propagation Delay, TTL Inputs <sup>(10)</sup>	0 – 5 V <sub>IN</sub> , 1V/ns Slew Rate	10	19	34	ns
	Propagation Matching Between Channels	INA=INB, OUTA and OUTB at 50% Point		1	2	ns
I <sub>RVS</sub>	Output Reverse Current Withstand <sup>(9)</sup>			500		mA

Continued on the following page...

## **Electrical Characteristics** (Continued)

Unless otherwise noted,  $V_{DD}$ =12 V,  $T_J$ =-40°C to +125°C. Currents are defined as positive into the device and negative out of the device.

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit				
Outputs (co	Outputs (continued)									
FAN3216TM	IX_F085, FAN3217TMX_F085 (Automotive-	Qualified Versions)								
t <sub>D1</sub> , t <sub>D2</sub>	Output Propagation Delay, TTL Inputs <sup>(11)</sup>	0 – 5 V <sub>IN</sub> , 1 V/ns Slew Rate	4.5	19.0	34.0	ns				
	Propagation Matching Between Channels <sup>(11)</sup>	INA=INB, OUTA and OUTB at 50% Point		2	4	ns				
V <sub>OH</sub>	High Level Output Voltage <sup>(11)</sup>	Voh =Vdd –Vout, lout=-1 mA		15	35	mV				
V <sub>OL</sub>	Low Level Output Voltage <sup>(11)</sup>	louт=1 mA		10	25	mV				

#### Notes:

- 9. Not tested in production.
- 10. See Timing Diagrams of Figure 8 and Figure 9.
- 11. Apply to only F085 Version

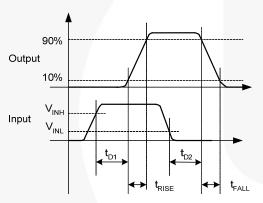


Figure 8. Non-Inverting Timing Diagram

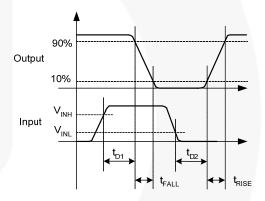
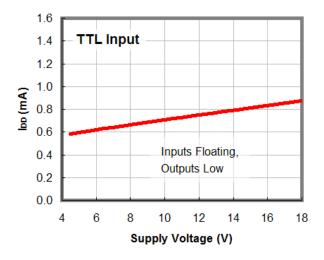


Figure 9. Inverting Timing Diagram

Typical characteristics are provided at T<sub>A</sub>=25°C and V<sub>DD</sub>=12 V unless otherwise noted.



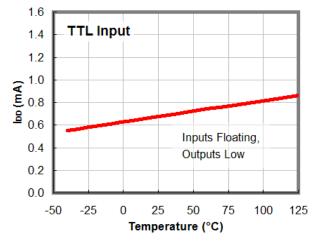
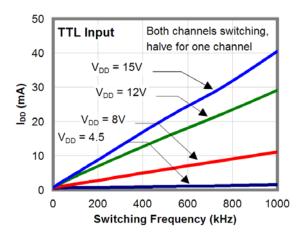


Figure 10. I<sub>DD</sub> (Static) vs. Supply Voltage<sup>(12)</sup>

Figure 11. I<sub>DD</sub> (Static) vs. Temperature<sup>(12)</sup>



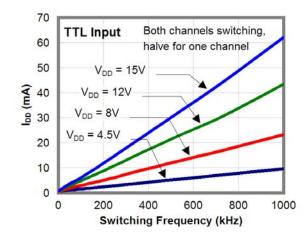
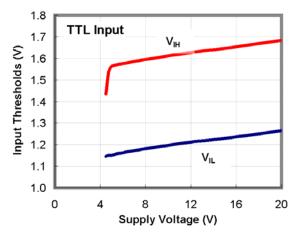


Figure 12. I<sub>DD</sub> (No-Load) vs. Frequency

Figure 13. I<sub>DD</sub> (1 nF Load) vs. Frequency



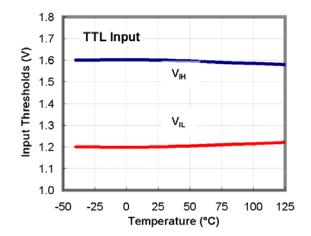


Figure 14. Input Thresholds vs. Supply Voltage

Figure 15. Input Thresholds vs. Temperature

Typical characteristics are provided at  $T_A$ =25°C and  $V_{DD}$ =12 V unless otherwise noted.

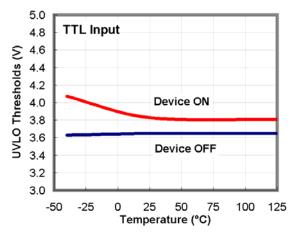


Figure 16. UVLO Threshold vs. Temperature

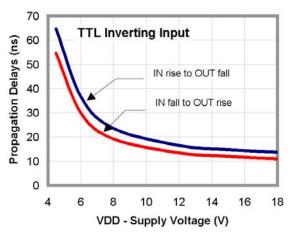


Figure 17. Propagation Delay vs. Supply Voltage

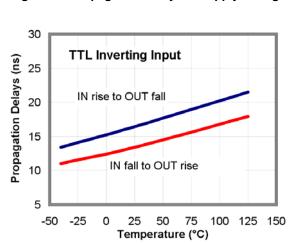


Figure 19. Propagation Delays vs. Temperature

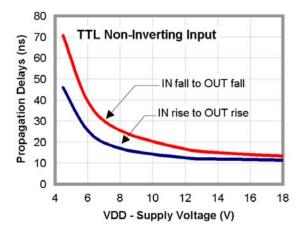


Figure 18. Propagation Delay vs. Supply Voltage

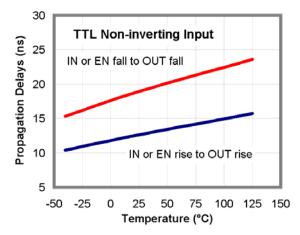
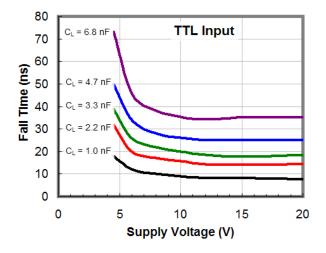


Figure 20. Propagation Delays vs. Temperature

Typical characteristics are provided at  $T_A$ =25°C and  $V_{DD}$ =12 V unless otherwise noted.



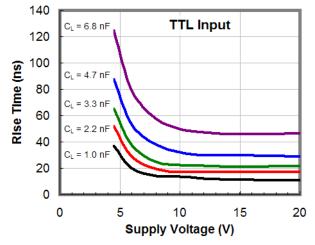


Figure 21. Fall Time vs. Supply Voltage

Figure 22. Rise Time vs. Supply Voltage

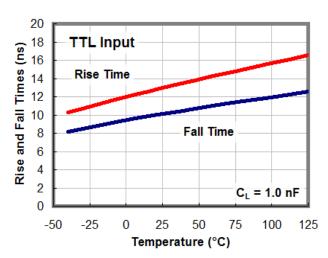


Figure 23. Rise and Fall Times vs. Temperature

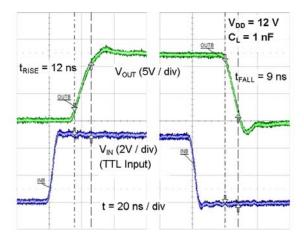


Figure 24. Rise/Fall Waveforms with 2.2 nF Load

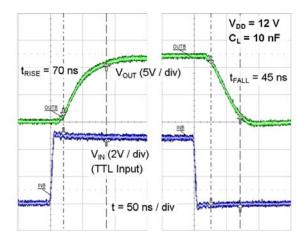


Figure 25. Rise/Fall Waveforms with 10 nF Load

Typical characteristics are provided at  $T_A=25^{\circ}C$  and  $V_{DD}=12~V$  unless otherwise noted.

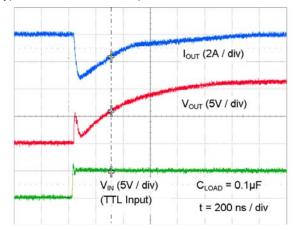


Figure 26. Quasi-Static Source Current with  $V_{DD}$ =12  $V^{(13)}$ 

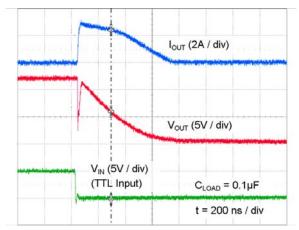


Figure 27. Quasi-Static Sink Current with V<sub>DD</sub>=12 V<sup>(13)</sup>

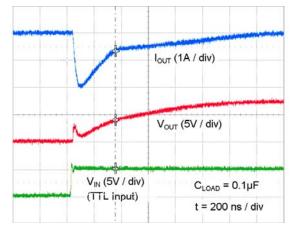


Figure 28. Quasi-Static Source Current with V<sub>DD</sub>=8 V<sup>(13)</sup>

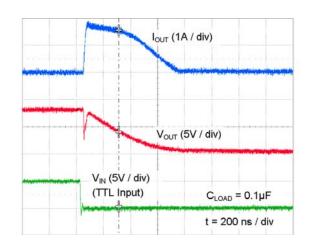


Figure 29. Quasi-Static Sink Current with V<sub>DD</sub>=8 V<sup>(13)</sup>

#### Notes:

- 12. For any inverting inputs pulled low, non-inverting inputs pulled high, or outputs driven high; static IDD increases by the current flowing through the corresponding pull-up/down resistor shown in Figure 6 and Figure 7.
- 13. The initial spike in each current waveform is a measurement artifact caused by the stray inductance of the current-measurement loop.

#### **Test Circuit**

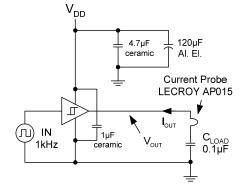


Figure 30. Quasi-Static I<sub>OUT</sub> / V<sub>OUT</sub> Test Circuit

## **Applications Information**

#### **Input Thresholds**

The FAN3216 and the FAN3217 drivers consist of two identical channels that may be used independently at rated current or connected in parallel to double the individual current capacity.

The input thresholds meet industry-standard TTL-logic thresholds independent of the  $V_{DD}$  voltage, and there is a hysteresis voltage of approximately 0.4 V. These levels permit the inputs to be driven from a range of input logic signal levels for which a voltage over 2 V is considered logic HIGH. The driving signal for the TTL inputs should have fast rising and falling edges with a slew rate of 6 V/ $\mu$ s or faster, so a rise time from 0 to 3.3 V should be 550 ns or less. With reduced slew rate, circuit noise could cause the driver input voltage to exceed the hysteresis voltage and retrigger the driver input, causing erratic operation.

## **Static Supply Current**

In the  $l_{DD}$  (static) typical performance characteristics shown in Figure 10 and Figure 11, each curve is produced with both inputs floating and both outputs LOW to indicate the lowest static  $l_{DD}$  current. For other states, additional current flows through the  $100 k\Omega$  resistors on the inputs and outputs shown in the block diagram of each part (see Figure 6 and Figure 7). In these cases, the actual static  $l_{DD}$  current is the value obtained from the curves plus this additional current.

### MillerDrive™ Gate Drive Technology

FAN3216 and FAN3217 gate drivers incorporate the MillerDrive  $^{\rm TM}$  architecture shown in Figure 31. For the output stage, a combination of bipolar and MOS devices provide large currents over a wide range of supply voltage and temperature variations. The bipolar devices carry the bulk of the current as OUT swings between 1/3 to 2/3  $V_{\rm DD}$  and the MOS devices pull the output to the HIGH or LOW rail.

The purpose of the MillerDrive™ architecture is to speed up switching by providing high current during the Miller plateau region when the gate-drain capacitance of the MOSFET is being charged or discharged as part of the turn-on / turn-off process.

For applications with zero voltage switching during the MOSFET turn-on or turn-off interval, the driver supplies high peak current for fast switching even though the Miller plateau is not present. This situation often occurs in synchronous rectifier applications because the body diode is generally conducting before the MOSFET is switched ON.

The output pin slew rate is determined by  $V_{\text{DD}}$  voltage and the load on the output. It is not user adjustable, but a series resistor can be added if a slower rise or fall time at the MOSFET gate is needed.

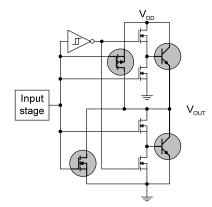


Figure 31. MillerDrive™ Output Architecture

#### **Under-Voltage Lockout**

The FAN321x startup logic is optimized to drive ground-referenced N-channel MOSFETs with an under-voltage lockout (UVLO) function to ensure that the IC starts up in an orderly fashion. When  $V_{\text{DD}}$  is rising, yet below the 3.9 V operational level, this circuit holds the output LOW, regardless of the status of the input pins. After the part is active, the supply voltage must drop 0.2 V before the part shuts down. This hysteresis helps prevent chatter when low  $V_{\text{DD}}$  supply voltages have noise from the power switching. This configuration is not suitable for driving high-side P-channel MOSFETs because the low output voltage of the driver would turn the P-channel MOSFET on with  $V_{\text{DD}}$  below 3.9 V.

## **V**<sub>DD</sub> Bypass Capacitor Guidelines

To enable this IC to turn a device ON quickly, a local high-frequency bypass capacitor,  $C_{BYP}$ , with low ESR and ESL should be connected between the VDD and GND pins with minimal trace length. This capacitor is in addition to bulk electrolytic capacitance of 10  $\mu$ F to 47  $\mu$ F commonly found on driver and controller bias circuits.

A typical criterion for choosing the value of  $C_{BYP}$  is to keep the ripple voltage on the  $V_{DD}$  supply to  $\leq 5\%$ . This is often achieved with a value  $\geq 20$  times the equivalent load capacitance  $C_{EQV}$ , defined here as  $Q_{GATE}/V_{DD}$ . Ceramic capacitors of 0.1  $\mu F$  to 1  $\mu F$  or larger are common choices, as are dielectrics, such as X5R and X7R, with good temperature characteristics and high pulse current capability.

If circuit noise affects normal operation, the value of  $C_{BYP}$  may be increased, to 50-100 times the  $C_{EQV}$ , or  $C_{BYP}$  may be split into two capacitors. One should be a larger value, based on equivalent load capacitance, and the other a smaller value, such as 1-10 nF mounted closest to the VDD and GND pins to carry the higher-frequency components of the current pulses. The bypass capacitor must provide the pulsed current from both of the driver channels and, if the drivers are switching simultaneously, the combined peak current sourced from the  $C_{BYP}$  would be twice as large as when a single channel is switching.

## **Layout and Connection Guidelines**

The FAN3216 and FAN3217 gate drivers incorporate fast-reacting input circuits, short propagation delays, and powerful output stages capable of delivering current peaks over 2 A to facilitate voltage transition times from under 10 ns to over 150 ns. The following layout and connection guidelines are strongly recommended:

- Keep high-current output and power ground paths separate from logic input signals and signal ground paths. This is especially critical for TTL-level logic thresholds at driver input pins.
- Keep the driver as close to the load as possible to minimize the length of high-current traces. This reduces the series inductance to improve highspeed switching, while reducing the loop area that can radiate EMI to the driver inputs and surrounding circuitry.
- If the inputs to a channel are not externally connected, the internal 100 kΩ resistors indicated on block diagrams command a low output. In noisy environments, it may be necessary to tie inputs of an unused channel to VDD or GND using short traces to prevent noise from causing spurious output switching.
- Many high-speed power circuits can be susceptible to noise injected from their own output or other external sources, possibly causing output retriggering. These effects can be obvious if the circuit is tested in breadboard or non-optimal circuit layouts with long input or output leads. For best results, make connections to all pins as short and direct as possible.
- FAN3216 and FAN3217 are pin-compatible with many other industry-standard drivers.
- The turn-on and turn-off current paths should be minimized, as discussed in the following section.

Figure 32 shows the pulsed gate drive current path when the gate driver is supplying gate charge to turn the MOSFET on. The current is supplied from the local bypass capacitor,  $C_{BYP}$ , and flows through the driver to the MOSFET gate and to ground. To reach the high peak currents possible, the resistance and inductance in the path should be minimized. The localized  $C_{BYP}$  acts to contain the high peak current pulses within this driver-MOSFET circuit, preventing them from disturbing the sensitive analog circuitry in the PWM controller.

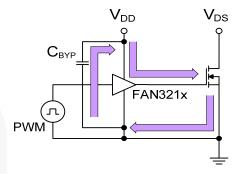


Figure 32. Current Path for MOSFET Turn-On

Figure 33 shows the current path when the gate driver turns the MOSFET OFF. Ideally, the driver shunts the current directly to the source of the MOSFET in a small circuit loop. For fast turn-off times, the resistance and inductance in this path should be minimized.

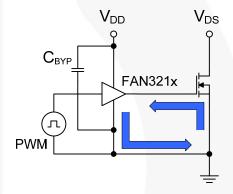


Figure 33. Current Path for MOSFET Turn-Off

#### **Operational Waveforms**

At power-up, the driver output remains LOW until the  $V_{DD}$  voltage reaches the turn-on threshold. The magnitude of the OUT pulses rises with  $V_{DD}$  until steady-state  $V_{DD}$  is reached. The non-inverting operation illustrated in Figure 34 shows that the output remains LOW until the UVLO threshold is reached, then the output is in-phase with the input.

The inverting configuration of startup waveforms are shown in Figure 35. With IN+ tied to VDD and the input signal applied to IN-, the OUT pulses are inverted with respect to the input. At power-up, the inverted output remains LOW until the  $V_{\text{DD}}$  voltage reaches the turn-on threshold, then it follows the input with inverted phase.

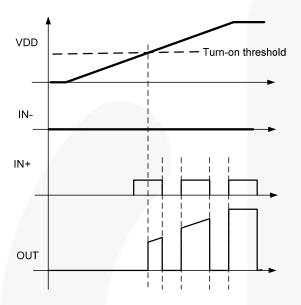


Figure 34. Non-Inverting Startup Waveforms

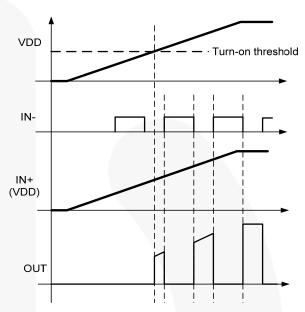


Figure 35. Inverting Startup Waveforms

#### **Thermal Guidelines**

Gate drivers used to switch MOSFETs and IGBTs at high frequencies can dissipate significant amounts of power. It is important to determine the driver power dissipation and the resulting junction temperature in the application to ensure that the part is operating within acceptable temperature limits.

The total power dissipation in a gate driver is the sum of two components,  $P_{GATE}$  and  $P_{DYNAMIC}$ :

$$P_{TOTAL} = P_{GATE} + P_{DYNAMIC}$$
 (1)

Gate Driving Loss: The most significant power loss results from supplying gate current (charge per unit time) to switch the load MOSFET on and off at the switching frequency. The power dissipation that results from driving a MOSFET at a specified gate-source voltage,  $V_{\rm GS}$ , with gate charge,  $Q_{\rm G}$ , at switching frequency,  $f_{\rm SW}$ , is determined by:

$$P_{GATE} = Q_G \cdot V_{GS} \cdot f_{SW} \cdot n \tag{2}$$

where n is the number of driver channels in use (1 or 2).

Dynamic Pre-Drive / Shoot-through Current: A power loss resulting from internal current consumption under dynamic operating conditions, including pin pull-up / pull-down resistors, can be obtained using the graphs in Typical Performance Characteristics to determine the current  $I_{\mbox{\scriptsize DYNAMIC}}$  drawn from  $V_{\mbox{\scriptsize DD}}$  under actual operating conditions:

$$P_{DYNAMIC} = I_{DYNAMIC} \cdot V_{DD} \cdot n \tag{3}$$

Once the power dissipated in the driver is determined, the driver junction rise with respect to circuit board can be evaluated using the following thermal equation, assuming  $\psi_{JB}$  was determined for a similar thermal design (heat sinking and air flow):

$$T_{J} = P_{TOTAL} \cdot \psi_{JB} + T_{B}$$
 (4)

where:

T<sub>J</sub> = driver junction temperature;

 Ψ<sub>JB</sub> = (psi) thermal characterization parameter relating temperature rise to total power dissipation; and

T<sub>B</sub> = board temperature in location as defined in the Thermal Characteristics table.

In the forward converter with synchronous rectifier shown in the typical application diagrams, the FDMS8660S is a reasonable MOSFET selection. The gate charge for each SR MOSFET would be 60 nC with  $V_{\rm GS} = V_{\rm DD} = 7V$ . At a switching frequency of 500 kHz, the total power dissipation is:

$$P_{GATE} = 60 \text{ nC} \cdot 7 \text{ V} \cdot 500 \text{ kHz} \cdot 2 = 0.42 \text{ W}$$
 (5)

$$P_{DYNAMIC} = 3 \text{ mA} \cdot 7 \text{ V} \cdot 2 = 0.042 \text{ W}$$
 (6)

$$P_{TOTAL} = 0.46 \text{ W} \tag{7}$$

The SOIC-8 has a junction-to-board thermal characterization parameter of  $\psi_{JB}=43^{\circ}\text{C/W}$ . In a system application, the localized temperature around the device is a function of the layout and construction of the PCB along with airflow across the surfaces. To ensure reliable operation, the maximum junction temperature of the device must be prevented from exceeding the maximum rating of 150°C; with 80% derating,  $T_J$  would be limited to 120°C. Rearranging Equation 4 determines the board temperature required to maintain the junction temperature below 120°C:

$$T_{B} = T_{J} - P_{TOTAL} \cdot \psi_{JB}$$
 (8)

$$T_B = 120^{\circ}C - 0.46 \text{ W} \cdot 43^{\circ}C/W = 100^{\circ}C$$
 (9)

## **Typical Application Diagrams**

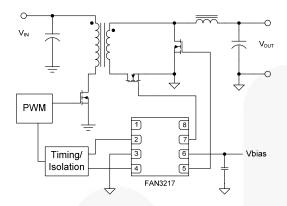


Figure 36. Forward Converter with Synchronous Rectification

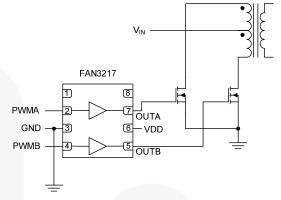


Figure 37. Primary-Side Dual Driver in a Push-Pull Converter

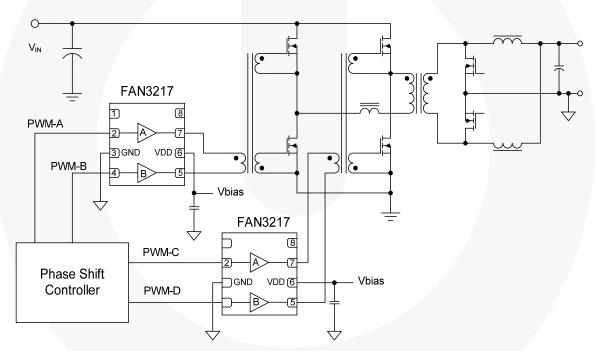


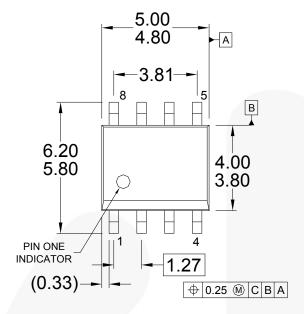
Figure 38. Phase-Shifted Full-Bridge with Two Gate Drive Transformers (Simplified)

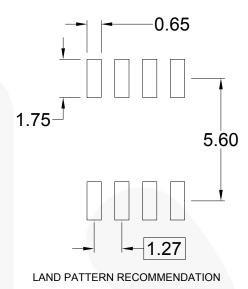
**Table 1. Related Products** 

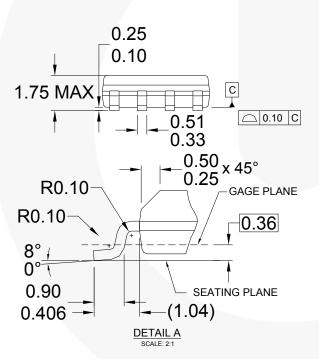
Туре	Part Number	Gate Drive <sup>(14)</sup> (Sink/Src)	Input Threshold	Logic	Package
Single 1 A	FAN3111C	+1.1 A / -0.9 A	CMOS	Single Channel of Dual-Input/Single-Output	SOT23-5, MLP6
Single 1 A	FAN3111E	+1.1 A / -0.9 A	External <sup>(15)</sup>	Single Non-Inverting Channel with External Reference	SOT23-5, MLP6
Single 2 A	FAN3100C	+2.5 A / -1.8 A	CMOS	Single Channel of Two-Input/One-Output	SOT23-5, MLP6
Single 2 A	FAN3100T	+2.5 A / -1.8 A	TTL	Single Channel of Two-Input/One-Output	SOT23-5, MLP6
Single 2 A	FAN3180	+2.4 A / -1.6 A	TTL	Single Non-Inverting Channel + 3.3-V LDO	SOT23-5
Dual 2 A	FAN3216T	+2.4 A / -1.6 A	TTL	Dual Inverting Channels	SOIC8
Dual 2 A	FAN3217T	+2.4 A / -1.6 A	TTL	Dual Non-Inverting Channels	SOIC8
Dual 2 A	FAN3226C	+2.4 A / -1.6 A	CMOS	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3226T	+2.4 A / -1.6 A	TTL	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3227C	+2.4 A / -1.6 A	CMOS	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3227T	+2.4 A / -1.6 A	TTL	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 2 A	FAN3228C	+2.4 A / -1.6 A	CMOS	Dual Channels of Two-Input/One-Output, Pin Config.1	SOIC8, MLP8
Dual 2 A	FAN3228T	+2.4 A / -1.6 A	TTL	Dual Channels of Two-Input/One-Output, Pin Config.1	SOIC8, MLP8
Dual 2 A	FAN3229C	+2.4 A / -1.6 A	CMOS	Dual Channels of Two-Input/One-Output, Pin Config.2	SOIC8, MLP8
Dual 2 A	FAN3229T	+2.4 A / -1.6 A	TTL	Dual Channels of Two-Input/One-Output, Pin Config.2	SOIC8, MLP8
Dual 2 A	FAN3268T	+2.4 A / -1.6 A	TTL	20 V Non-Inverting Channel (NMOS) and Inverting Channel (PMOS) + Dual Enables	SOIC8
Dual 2 A	FAN3278T	+2.4 A / -1.6 A	TTL	30 V Non-Inverting Channel (NMOS) and Inverting Channel (PMOS) + Dual Enables	SOIC8
Dual 4 A	FAN3213T	+2.5 A / -1.8 A	TTL	Dual Inverting Channels	SOIC8
Dual 4 A	FAN3214T	+2.5 A / -1.8 A	TTL	Dual Non-Inverting Channels	SOIC8
Dual 4 A	FAN3223C	+4.3 A / -2.8 A	CMOS	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3223T	+4.3 A / -2.8 A	TTL	Dual Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3224C	+4.3 A / -2.8 A	CMOS	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3224T	+4.3 A / -2.8 A	TTL	Dual Non-Inverting Channels + Dual Enable	SOIC8, MLP8
Dual 4 A	FAN3225C	+4.3 A / -2.8 A	CMOS	Dual Channels of Two-Input/One-Output	SOIC8, MLP8
Dual 4 A	FAN3225T	+4.3 A / -2.8 A	TTL	Dual Channels of Two-Input/One-Output	SOIC8, MLP8
Single 9 A	FAN3121C	+9.7 A / -7.1 A	CMOS	Single Inverting Channel + Enable	SOIC8, MLP8
Single 9 A	FAN3121T	+9.7 A / -7.1 A	TTL	Single Inverting Channel + Enable	SOIC8, MLP8
Single 9 A	FAN3122T	+9.7 A / -7.1 A	CMOS	Single Non-Inverting Channel + Enable	SOIC8, MLP8
Single 9 A	FAN3122C	+9.7 A / -7.1 A	TTL	Single Non-Inverting Channel + Enable	SOIC8, MLP8
Dual 12 A	FAN3240	+12.0 A	TTL	Dual-Coil Relay Driver, Timing Config. 0	SOIC8
Dual 12 A	FAN3241	+12.0 A	TTL	Dual-Coil Relay Driver, Timing Config. 1	SOIC8

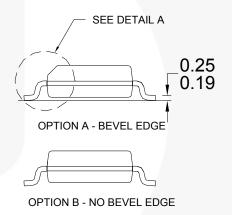
- 14. Typical currents with OUTx at 6 V and V<sub>DD</sub>=12 V.
  15. Thresholds proportional to an externally supplied reference voltage.

## **Physical Dimensions**









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Figure 39. 8-Lead Small Outline Integrated Circuit (SOIC)

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